



PCA9509

Level translating I²C-bus/SMBus repeater

Rev. 02 — 29 June 2007

Product data sheet

1. General description

The PCA9509 is a level translating I²C-bus/SMBus repeater that enables processor low voltage 2-wire serial bus to interface with standard I²C-bus or SMBus I/O. While retaining all the operating modes and features of the I²C-bus system during the level shifts, it also permits extension of the I²C-bus by providing bidirectional buffering for both the data (SDA) and the clock (SCL) lines, thus enabling the I²C-bus or SMBus maximum capacitance of 400 pF on the higher voltage side. The SDA and SCL pins are over-voltage tolerant and are high-impedance when the PCA9509 is unpowered.

The bus port B drivers are compliant with SMBus I/O levels, while port A uses a current sensing mechanism to detect the input or output LOW signal which prevents bus lock-up. Port A uses a 1 mA current source for pull-up and a 200 Ω pull-down driver. This results in a LOW on the port A accommodating smaller voltage swings. The output pull-down on the port A internal buffer LOW is set for approximately 0.2 V, while the input threshold of the internal buffer is set about 50 mV lower than that of the output voltage LOW. When the port A I/O is driven LOW internally, the LOW is not recognized as a LOW by the input. This prevents a lock-up condition from occurring. The output pull-down on the port B drives a hard LOW and the input level is set at 0.3 of SMBus or I²C-bus voltage level which enables port B to connect to any other I²C-bus devices or buffer.

The PCA9509 drivers are not enabled unless $V_{CC(A)}$ is above 0.8 V and $V_{CC(B)}$ is above 2.5 V. The enable (EN) pin can also be used to turn the drivers on and off under system control. Caution should be observed to only change the state of the EN pin when the bus is idle.

2. Features

- Bidirectional buffer isolates capacitance and allows 400 pF on port B of the device
- Voltage level translation from port A (1 V to $V_{CC(B)} - 1.0$ V) to port B (3.0 V to 5.5 V)
- Requires no external pull-up resistors on lower voltage port A
- Active HIGH repeater enable input
- Open-drain inputs/outputs
- Lock-up free operation
- Supports arbitration and clock stretching across the repeater
- Accommodates Standard-mode and Fast-mode I²C-bus devices and multiple masters
- Powered-off high-impedance I²C-bus pins
- Operating supply voltage range of 1.0 V to $V_{CC(B)} - 1.0$ V on port A, 3.0 V to 5.5 V on port B
- 5 V tolerant port B SCL, SDA and enable pins

- 0 Hz to 400 kHz clock frequency
Remark: The maximum system operating frequency may be less than 400 kHz because of the delays added by the repeater.
- ESD protection exceeds 2000 V HBM per JESD22-A114, 200 V MM per JESD22-A115, and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JEDEC Standard JESD78 which exceeds 100 mA
- Packages offered: TSSOP8, SO8, XQFN8

3. Ordering information

Table 1. Ordering information

| Type number | Topside mark | Package | | Version |
|-------------|--------------------|---------|--|----------|
| | | Name | Description | |
| PCA9509D | PCA9509 | SO8 | plastic small outline package; 8 leads; body width 3.9 mm | SOT96-1 |
| PCA9509DP | 9509 | TSSOP8 | plastic thin shrink small outline package; 8 leads; body width 3 mm | SOT505-1 |
| PCA9509GM | P9X ^[1] | XQFN8 | plastic extremely thin quad flat package; no leads; 8 terminals; body 1.6 × 1.6 × 0.5 mm | SOT902-1 |

[1] 'X' will change based on date code.

4. Functional diagram

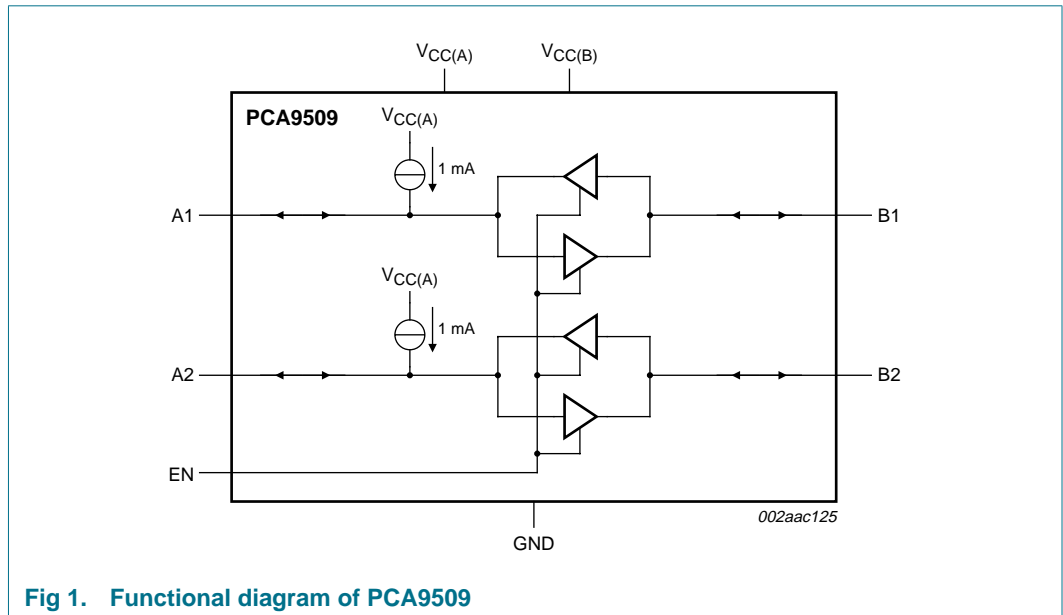
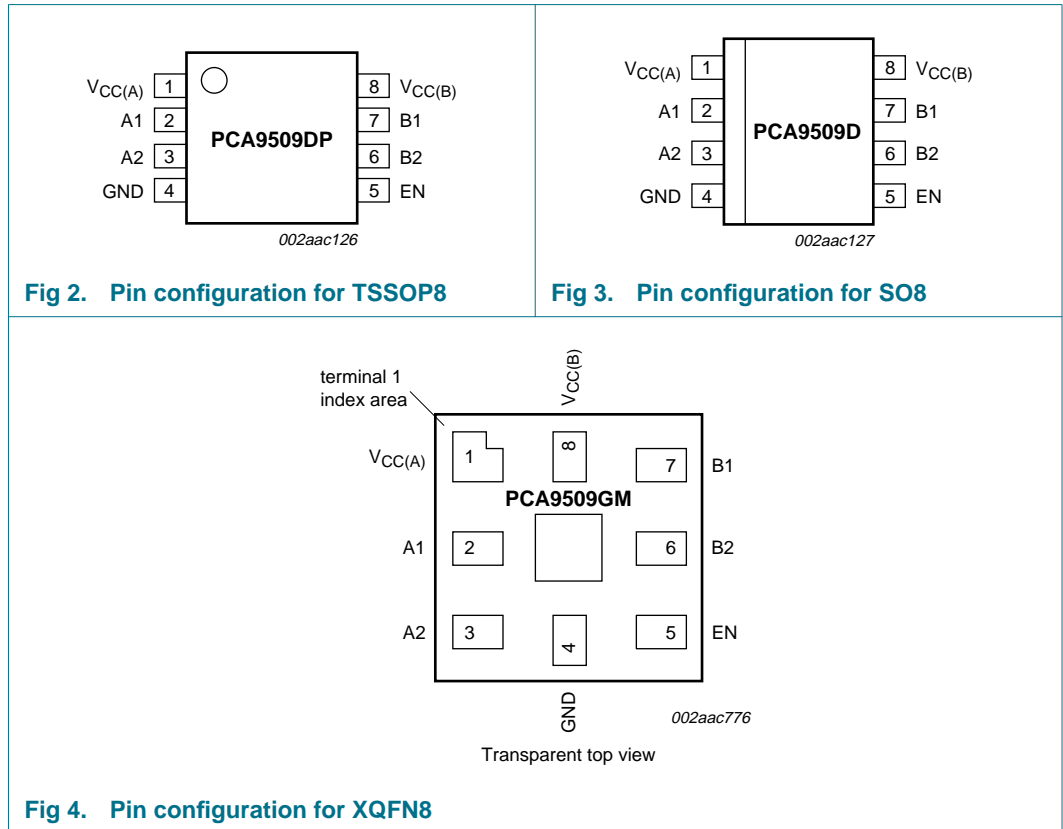


Fig 1. Functional diagram of PCA9509

5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|--------------------|-----|--|
| V _{CC(A)} | 1 | port A power supply |
| A1 ^[1] | 2 | port A (lower voltage side) |
| A2 ^[1] | 3 | port A |
| GND | 4 | ground (0 V) |
| EN | 5 | enable input (active HIGH) |
| B2 ^[1] | 6 | port B (SMBus/I ² C-bus side) |
| B1 ^[1] | 7 | port B |
| V _{CC(B)} | 8 | port B power supply |

[1] Port A and port B can be used for either SCL or SDA.

6. Functional description

Refer to [Figure 1 “Functional diagram of PCA9509”](#).

The PCA9509 enables I²C-bus or SMBus translation down to $V_{CC(A)}$ as low as 1.0 V without degradation of system performance. The PCA9509 contains 2 bidirectional open-drain buffers specifically designed to support up-translation/down-translation between the low voltage and 3.3 V SMBus or 5 V I²C-bus. The port B I/Os are over-voltage tolerant to 5.5 V even when the device is unpowered.

The PCA9509 includes a power-up circuit that keeps the output drivers turned off until $V_{CC(B)}$ is above 2.5 V and the $V_{CC(A)}$ is above 0.8 V. $V_{CC(B)}$ and $V_{CC(A)}$ can be applied in any sequence at power-up. After power-up and with the EN pin HIGH, a LOW level on port A (below approximately 0.15 V) turns the corresponding port B driver (either SDA or SCL) on and drives port B down to about 0 V. When port A rises above approximately 0.15 V, the port B pull-down driver is turned off and the external pull-up resistor pulls the pin HIGH. When port B falls first and goes below $0.3V_{CC(B)}$, the port A driver is turned on and port A pulls down to 0.2 V (typical). The port B pull-down is not enabled unless the port A voltage goes below V_{ILC} . If the port A low voltage goes below V_{ILC} , the port B pull-down driver is enabled until port A rises above approximately 0.15 V (V_{ILC}), then port B, if not externally driven LOW, will continue to rise being pulled up by the external pull-up resistor.

Remark: Ground offset between the PCA9509 ground and the ground of devices on port A of the PCA9509 must be avoided.

The reason for this cautionary remark is that a CMOS/NMOS open-drain capable of sinking 3 mA of current at 0.4 V will have an output resistance of 133 Ω or less ($R = E / I$). Such a driver will share enough current with the port A output pull-down of the PCA9509 to be seen as a LOW as long as the ground offset is zero. If the ground offset is greater than 0 V, then the driver resistance must be less. Since V_{ILC} can be as low as 90 mV at cold temperatures and the low end of the current distribution, the maximum ground offset should not exceed 50 mV.

Bus repeaters that use an output offset are not interoperable with the port A of the PCA9509 as their output LOW levels will not be recognized by the PCA9509 as a LOW. If the PCA9509 is placed in an application where the V_{IL} of port A of the PCA9509 does not go below its V_{ILC} it will pull port B LOW initially when port A input transitions LOW but the port B will return HIGH, so it will not reproduce the port A input on port B. Such applications should be avoided.

Port B is interoperable with all I²C-bus slaves, masters and repeaters.

6.1 Enable

The EN pin is active HIGH and allows the user to select when the repeater is active. This can be used to isolate a badly behaved slave on power-up until after the system power-up reset. It should never change state during an I²C-bus operation because disabling during a bus operation will hang the bus and enabling part way through a bus cycle could confuse the I²C-bus parts being enabled.

The enable pin should only change state when the bus and the repeater port are in an idle state to prevent system failures.

6.2 I²C-bus systems

As with the standard I²C-bus system, pull-up resistors are required to provide the logic HIGH levels on the buffered bus (standard open-collector configuration of the I²C-bus). The size of these pull-up resistors depends on the system. Each of the port A I/Os has an internal pull-up current source and does not require the external pull-up resistor. Port B is designed to work with Standard-mode and Fast-mode I²C-bus devices in addition to SMBus devices. Standard-mode I²C-bus devices only specify 3 mA output drive; this limits the termination current to 3 mA in a generic I²C-bus system where Standard-mode devices and multiple masters are possible. Under certain conditions higher termination currents can be used.

7. Application design-in information

A typical application is shown in [Figure 5](#). In this example, the CPU is running on a 1.1 V I²C-bus while the master is connected to a 3.3 V bus. Both buses run at 400 kHz. Master devices can be placed on either bus.

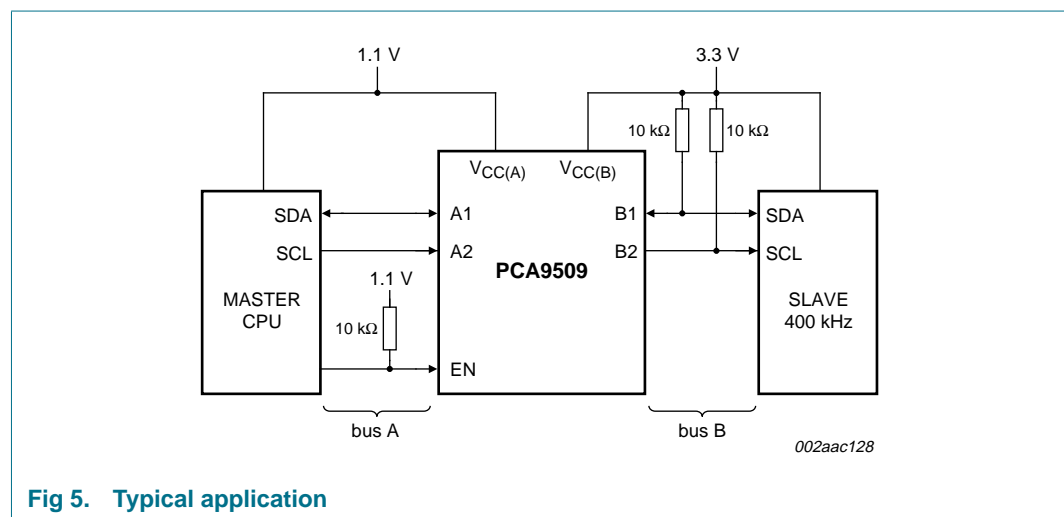


Fig 5. Typical application

When port B of the PCA9509 is pulled LOW by a driver on the I²C-bus, a CMOS hysteresis detects the falling edge when it goes below $0.3V_{CC(B)}$ and causes the internal driver on port A to turn on, causing port A to pull down to about 0.2 V. When port A of the PCA9509 falls, first a comparator detects the falling edge and causes the internal driver on port B to turn on and pull the port B pin down to ground. In order to illustrate what would be seen in a typical application, refer to [Figure 6](#) and [Figure 7](#). If the bus master in [Figure 5](#) were to write to the slave through the PCA9509, waveforms shown in [Figure 6](#) would be observed on the B bus. This looks like a normal I²C-bus transmission.

On the A bus side of the PCA9509, the clock and data lines would have a positive offset from ground equal to the V_{OL} of the PCA9509. After the 8th clock pulse, the data line will be pulled to the V_{OL} of the master device, which is very close to ground in this example. At the end of the acknowledge, the level rises only to the LOW level set by the driver in the PCA9509 for a short delay while the B bus side rises above $0.5V_{CC(B)}$, then it continues HIGH. It is important to note that any arbitration or clock stretching events require that the LOW level on the A bus side at the input of the PCA9509 (V_{IL}) is below V_{ILC} to be recognized by the PCA9509 and then transmitted to the B bus side.

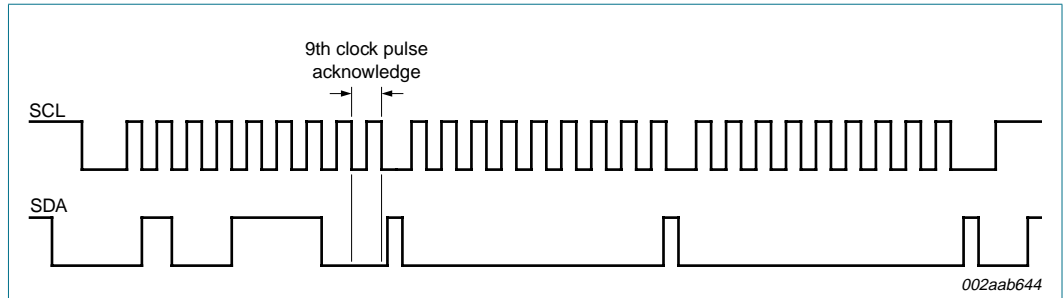


Fig 6. Bus B SMBus/I²C-bus waveform

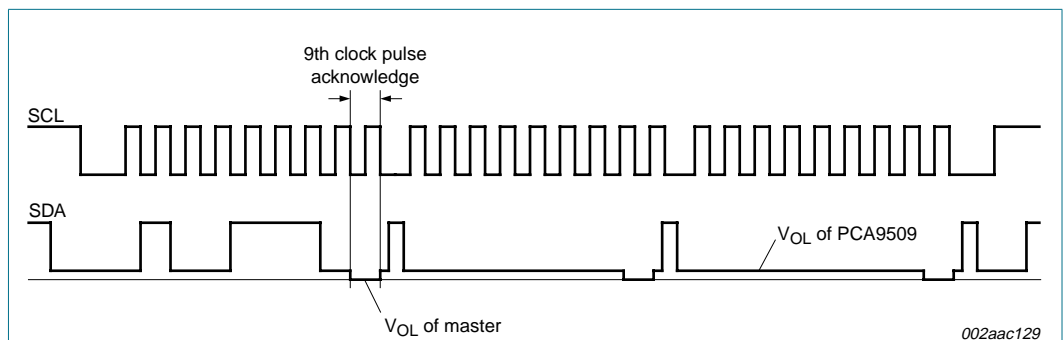


Fig 7. Bus A lower voltage waveform

8. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------|--------------------------------|-------------------------|------|------|------|
| V _{CC(B)} | supply voltage port B | | -0.5 | +6.0 | V |
| V _{CC(A)} | supply voltage port A | | -0.5 | +6.0 | V |
| V _{I/O} | voltage on an input/output pin | port A | -0.5 | +6.0 | V |
| | | port B; enable pin (EN) | -0.5 | +6.0 | V |
| I _{I/O} | input/output current | | - | ±20 | mA |
| I _I | input current | | - | ±20 | mA |
| P _{tot} | total power dissipation | | - | 100 | mW |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| T _{amb} | ambient temperature | operating in free air | -40 | +85 | °C |
| T _j | junction temperature | | - | +125 | °C |
| T _{sp} | solder point temperature | 10 s max. | - | 300 | °C |

9. Static characteristics

Table 4. Static characteristics

GND = 0 V; T_{amb} = -40 °C to +85 °C; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ ^[1] | Max | Unit |
|--|--|--|-----------------------|--------------------|------------------------|------|
| Supplies | | | | | | |
| V _{CC(B)} | supply voltage port B | | 3.0 | - | 5.5 | V |
| V _{CC(A)} | supply voltage port A | | 1.0 | - | V _{CC(B)} - 1 | V |
| I _{CC(A)} | supply current port A | all port A static HIGH | 0.25 | 0.45 | 0.9 | mA |
| | | all port A static LOW | 1.25 | 3.0 | 5 | mA |
| I _{CC(B)} | supply current port B | all port B static HIGH | 0.5 | 0.9 | 1.1 | mA |
| Input and output of port A (A1 to A2) | | | | | | |
| V _{IH} | HIGH-level input voltage | port A | 0.7V _{CC(A)} | - | V _{CC(A)} | V |
| V _{IL} | LOW-level input voltage | port A | ^[2] -0.5 | - | +0.3 | V |
| V _{ILc} | contention LOW-level input voltage | | ^[2] -0.5 | +0.15 | - | V |
| V _{IK} | input clamping voltage | I _L = -18 mA | -1.5 | - | -0.5 | V |
| I _{LI} | input leakage current | V _I = V _{CC(A)} | - | - | ±1 | µA |
| I _{IL} | LOW-level input current | | ^[3] -1.5 | -1.0 | -0.45 | mA |
| V _{OL} | LOW-level output voltage | | ^[4] - | 0.2 | 0.35 | V |
| V _{OL} -V _{ILc} | difference between LOW-level output and LOW-level input voltage contention | | ^[5] - | 50 | - | mV |
| I _{LOH} | HIGH-level output leakage current | V _O = 1.1 V | - | - | 10 | µA |
| C _{io} | input/output capacitance | | - | 6 | 7 | pF |
| Input and output of port B (B1 to B2) | | | | | | |
| V _{IH} | HIGH-level input voltage | port B | 0.7V _{CC(B)} | - | V _{CC(B)} | V |
| V _{IL} | LOW-level input voltage | port B | -0.5 | - | +0.3V _{CC(B)} | V |
| V _{IK} | input clamping voltage | I _L = -18 mA | -1.5 | - | -0.5 | V |
| I _{LI} | input leakage current | V _I = 3.6 V | -1.0 | - | +1.0 | µA |
| I _{IL} | LOW-level input current | V _I = 0.2 V | - | - | 10 | µA |
| V _{OL} | LOW-level output voltage | I _{OL} = 6 mA | - | 0.1 | 0.2 | V |
| I _{LOH} | HIGH-level output leakage current | V _O = 3.6 V | - | - | 10 | µA |
| C _{io} | input/output capacitance | | - | 3 | 5 | pF |
| Enable | | | | | | |
| V _{IL} | LOW-level input voltage | | -0.5 | - | +0.1V _{CC(A)} | V |
| V _{IH} | HIGH-level input voltage | | 0.9V _{CC(A)} | - | V _{CC(B)} | V |
| I _{IL(EN)} | LOW-level input current on pin EN | V _I = 0.2 V, EN; V _{CC} = 3.6 V | -1 | - | +1 | µA |
| I _{LI} | input leakage current | | -1 | - | +1 | µA |
| C _i | input capacitance | V _I = 3.0 V or 0 V | - | 2 | 3 | pF |

[1] Typical values with V_{CC(A)} = 1.1 V, V_{CC(B)} = 5.0 V.

[2] V_{IL} specification is for the falling edge seen by the port A input. V_{ILc} is for the static LOW levels seen by the port A input resulting in port B output staying LOW.

- [3] The port A current source has a typical value of about 1 mA, but varies with both $V_{CC(A)}$ and $V_{CC(B)}$. Below $V_{CC(A)}$ of about 0.7 V the port A current source current drops to 0 mA. The current source current dropping across the internal pull-down driver resistance of about 200 Ω defines the V_{OL} .
- [4] As long as the chip ground is common with the input ground reference the driver resistance may be as large as 120 Ω . However, ground offset will rapidly decrease the maximum allowed driver resistance.
- [5] Guaranteed by design.

10. Dynamic characteristics

Table 5. Dynamic characteristics

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|------------------------------------|---|----------|-----|------|------|
| $V_{CC(A)} = 1.1\text{ V}; V_{CC(B)} = 3.3\text{ V}$ | | | | | | |
| t_{PLH} | LOW-to-HIGH propagation delay | port B to port A | [1] 69 | 109 | 216 | ns |
| t_{PHL} | HIGH-to-LOW propagation delay | port B to port A | [1] 63 | 86 | 140 | ns |
| t_{TLH} | LOW to HIGH output transition time | port A | [1] 14 | 22 | 96 | ns |
| t_{THL} | HIGH to LOW output transition time | port A | [1] 5 | 8.1 | 16 | ns |
| t_{PLH} | LOW-to-HIGH propagation delay | port A to port B | [1] -69 | -91 | -139 | ns |
| t_{PLH2} | LOW to HIGH propagation delay 2 | port A to port B; measured from the 50 % of initial LOW on port A to 1.5 V rising on port B | [1] 91 | 153 | 226 | ns |
| t_{PHL} | HIGH-to-LOW propagation delay | port A to port B | [1] 73 | 122 | 183 | ns |
| t_{TLH} | LOW to HIGH output transition time | port B | [1][2] - | 61 | - | ns |
| t_{THL} | HIGH to LOW output transition time | port B | [1] 15 | 24 | 40 | ns |
| t_{su} | setup time | EN HIGH before START condition | 100 | - | - | ns |
| t_h | hold time | EN HIGH after STOP condition | 100 | - | - | ns |
| $V_{CC(A)} = 1.9\text{ V}; V_{CC(B)} = 5.0\text{ V}$ | | | | | | |
| t_{PLH} | LOW-to-HIGH propagation delay | port B to port A | [1] 69 | 105 | 216 | ns |
| t_{PHL} | HIGH-to-LOW propagation delay | port B to port A | [1] 63 | 86 | 140 | ns |
| t_{TLH} | LOW to HIGH output transition time | port A | [1] 14 | 27 | 96 | ns |
| t_{THL} | HIGH to LOW output transition time | port A | [1] 5 | 8 | 35 | ns |
| t_{PLH} | LOW-to-HIGH propagation delay | port A to port B | [1] -69 | -89 | -139 | ns |
| t_{PLH2} | LOW to HIGH propagation delay 2 | port A to port B; measured from the 50 % of initial LOW on port A to 1.5 V rising on port B | [1] 91 | 131 | 226 | ns |
| t_{PHL} | HIGH-to-LOW propagation delay | port A to port B | [1] 73 | 99 | 183 | ns |
| t_{TLH} | LOW to HIGH output transition time | port B | [1][2] - | 65 | - | ns |
| t_{THL} | HIGH to LOW output transition time | port B | [1] 15 | 31 | 40 | ns |
| t_{su} | setup time | EN HIGH before START condition | 100 | - | - | ns |
| t_h | hold time | EN HIGH after STOP condition | 100 | - | - | ns |

[1] Load capacitance = 50 pF; load resistance on port B = 1.35 k Ω .

[2] Value is determined by RC time constant of bus line.

10.1 AC waveforms

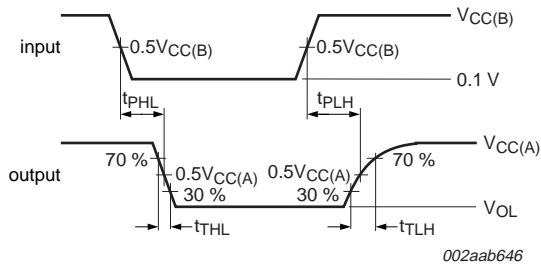


Fig 8. Propagation delay and transition times; port B to port A

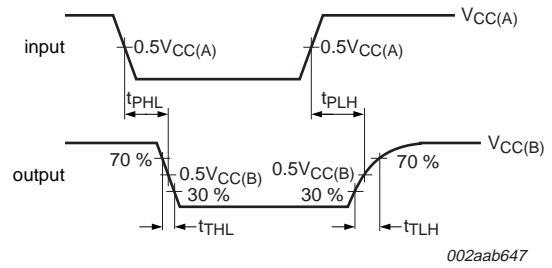


Fig 9. Propagation delay and transition times; port A to port B

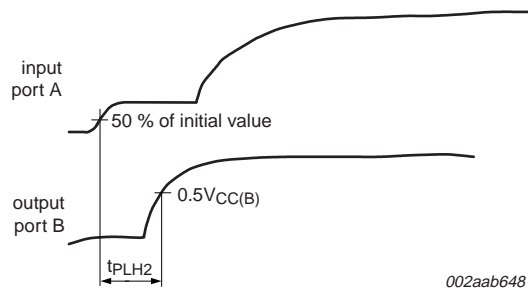
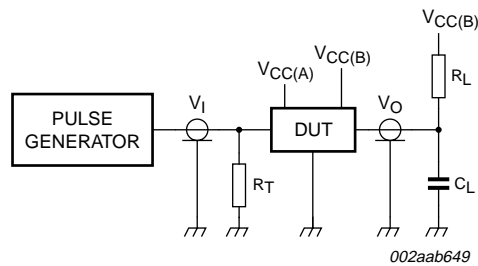


Fig 10. Propagation delay from the port A's external driver switching off to port B LOW-to-HIGH transition; port A to port B

11. Test information



R_L = load resistor; 1.35 k Ω on port B
 C_L = load capacitance includes jig and probe capacitance; 50 pF
 R_T = termination resistance should be equal to Z_o of pulse generators

Fig 11. Test circuit for open-drain outputs

12. Package outline

SO8: plastic small outline package; 8 leads; body width 3.9 mm

SOT96-1



Fig 12. Package outline SOT96-1 (SO8)

TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm

SOT505-1

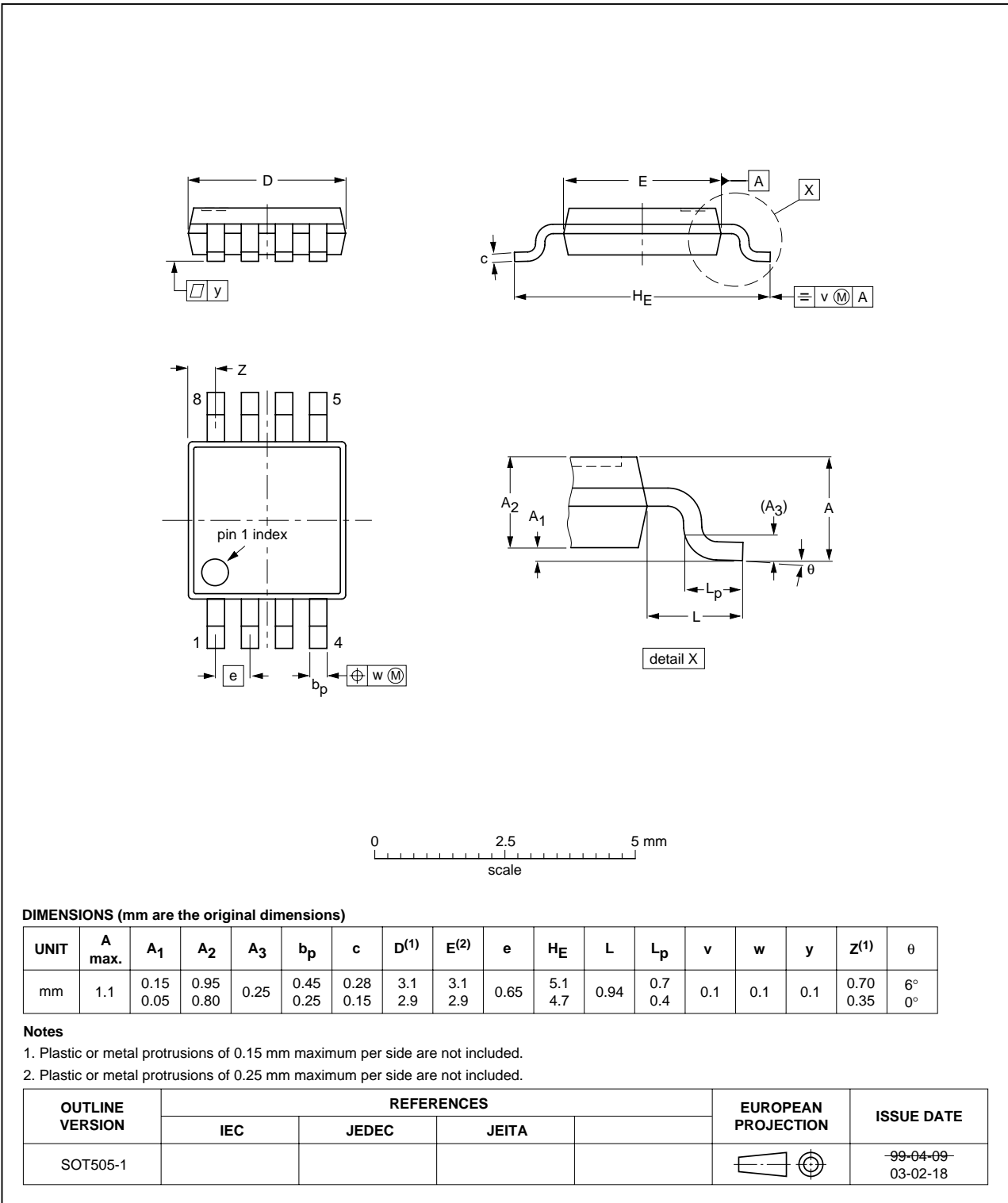


Fig 13. Package outline SOT505-1 (TSSOP8)

XQFN8: plastic extremely thin quad flat package; no leads; 8 terminals; body 1.6 x 1.6 x 0.5 mm

SOT902-1

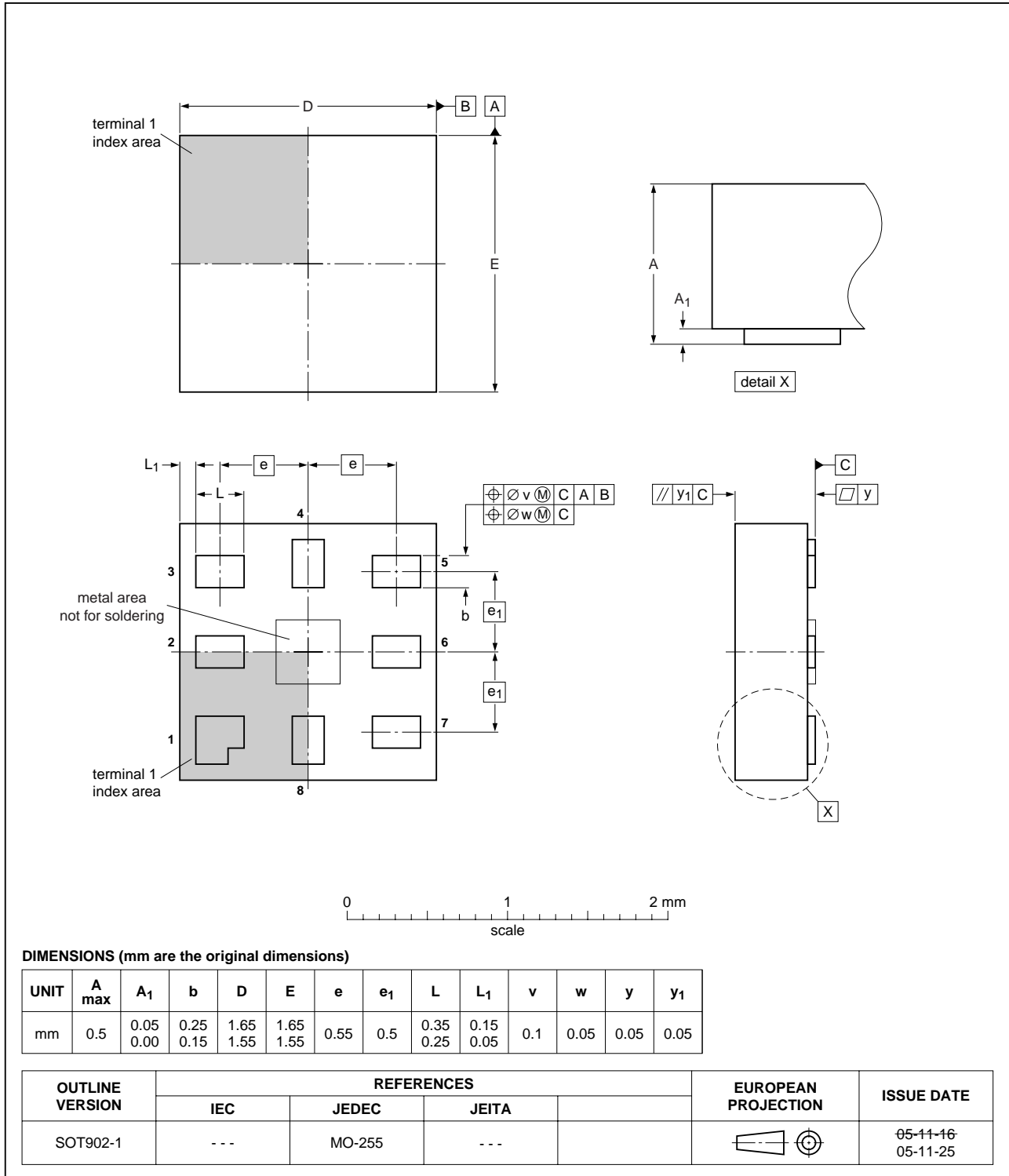


Fig 14. Package outline SOT902-1 (XQFN8)

13. Soldering

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

13.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

13.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus PbSn soldering

13.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

13.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 15](#)) than a PbSn process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 6](#) and [7](#)

Table 6. SnPb eutectic process (from J-STD-020C)

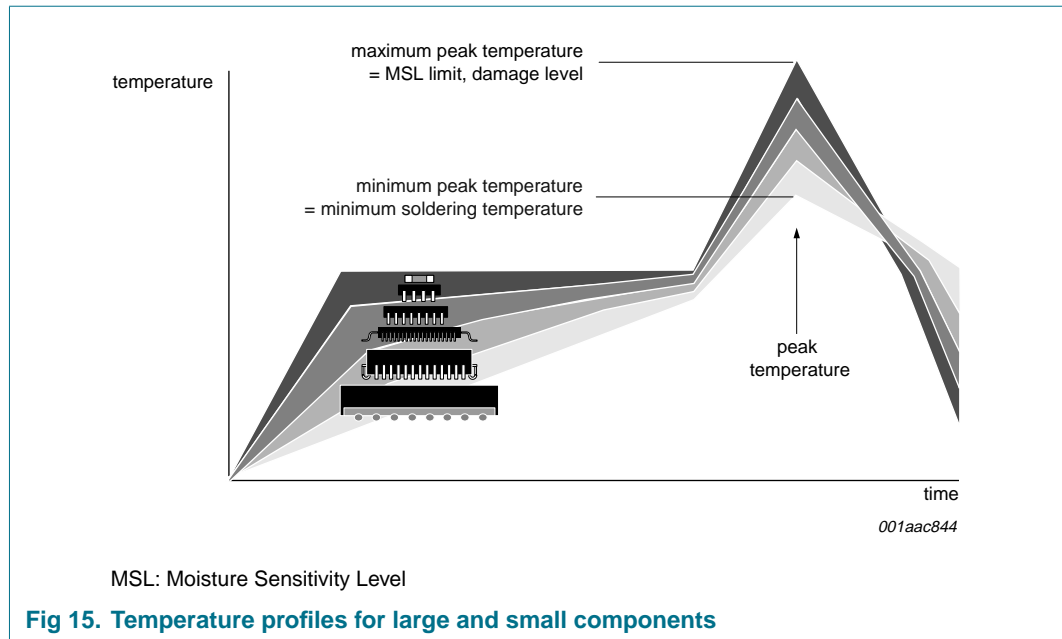
| Package thickness (mm) | Package reflow temperature (°C) | |
|------------------------|---------------------------------|-------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |
| ≥ 2.5 | 220 | 220 |

Table 7. Lead-free process (from J-STD-020C)

| Package thickness (mm) | Package reflow temperature (°C) | | |
|------------------------|---------------------------------|-------------|--------|
| | Volume (mm ³) | | |
| | < 350 | 350 to 2000 | > 2000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 15](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

14. Abbreviations

Table 8. Abbreviations

| Acronym | Description |
|----------------------|--|
| CDM | Charged Device Model |
| CMOS | Complementary Metal Oxide Semiconductor |
| CPU | Central Processing Unit |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| I/O | Input/Output |
| I ² C-bus | Inter-Integrated Circuit bus |
| MM | Machine Model |
| NMOS | Negative-channel Metal Oxide Semiconductor |
| RC | Resistor-Capacitor network |
| SMBus | System Management Bus |

15. Revision history

Table 9. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|---|--------------------|---------------|------------|
| PCA9509_2 | 20070629 | Product data sheet | - | PCA9509_1 |
| Modifications: | <ul style="list-style-type: none">• The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors.• Legal texts have been adapted to the new company name where appropriate.• Added XQFN8 package offering (affects Table 1 "Ordering information", Section 5.1 "Pinning", and Section 12 "Package outline") | | | |
| PCA9509_1 | 20060627 | Product data sheet | - | - |

16. Legal information

16.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

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